# C191HM <br> POWERMETER AND HARMONIC MANAGER 

## COMMUNICATIONS

ASCII Communications Protocol REFERENCE GUIDE

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This revision is applicable to the C191HM instruments with firmware version 4.21 and later.

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## 1 GENERAL

This document specifies the ASCII serial communications protocol used to transfer data between a master computer station and the C191HM. The document provides the complete information necessary to develop third-party communications software capable of communication with the Series C191HM instruments.

All messages within the ASCII communications protocol are designed to consist only of printable characters.

Additional information concerning communications operation, configuring the communications parameters and communications connections is found in "Series C191HM Powermeters, Installation and Operation Manual".

## IMPORTANT

1. In 3-wire connection schemes, the unbalanced current and phase readings for power factor, active power, and reactive power will be zeros, because they have no meaning. Only the total three-phase power values can be used.
2. In 4LN3, 4LL3, 3LN3 and 3LL3 wiring modes, harmonic voltages will represent line-to-neutral voltages. In a 3-wire direct connection, harmonic voltages will represent line-to-neutral voltages as they appear on the instrument's input transformers. In a 3-wire open delta connection, harmonic voltages will comprise L12 and L23 line-to-line voltages.

## 2 ASCII FRAMING

The following specifies the ASCII message frame:

| Field No. | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Contents | SYNC <br> $(!)$ | Message <br> length | Slave <br> address | Message <br> type | Message <br> body | Check sum | Trailer <br> (CRLF) |
| Length, char | 1 | 3 | 2 | 1 | 0 to 246 | 1 | 2 |

## SYNC

Synchronization character: one character '!' (ASCII 33), used for starting synchronization.

## Message length

The length of the message including only number of bytes in fields \#2, \#3, \#4 and \#5. Contains three characters between '006' and '252'.

## Slave address

Two characters between '00' and '99'. The instrument with address ' 00 ' responds to requests with any incoming address. For RS-422/RS-485 communications (multi-drop mode), this field must NEVER be zero.

## Message type

One character representing the type of a host request. A list of the message types is shown in Tables 2-1 and 2-2. Note that they are case-sensitive.

## Message body

Contains the message parameters in ASCII representation. All parameter fields have a fixed format. The data fields vary in length depending on the data type. Unless otherwise indicated, the parameters should be right justified and left-padded with zeros. Most parameters are represented in ASCII hexadecimal notation, and in some cases (to provide compatibility with old instruments) a decimal representation is preserved.

In a decimal notation, the parameters are transferred in a decimal representation as is, i.e., no conversion is needed. When a value is between 0 and 1 , a decimal point is placed in the data field. When the whole value exceeds the field range, it is divided by 1000 and truncated to the right. A decimal point is placed after the thousands to denote that the value has been truncated and must be multiplied by 1000 before it will be processed.

In a hexadecimal notation, all parameters are whole binary numbers of a 1-byte, 2-byte or 4-byte length. Each byte is transferred as two hexadecimal digits in ASCII notation (i.e., ASCII printable characters 0-9, A-F are used to represent hexadecimal digits $0 h-9 h, 0 a h-0 f h)$. Each byte is transmitted high order digit first. Each 2-byte and 4-byte parameter is transmitted high order bytes first. Negative numbers are transmitted in 2-complement code.

To represent numbers between 0 and 1, a modulus method is used. Fractional numbers are divided by a modulus and stored in the Powermeter as whole numbers. The modulus depends on the number of decimal digits in the fractional part, i.e., on the value precision. The modulus is given in the form $\times 0.1$, $\times 0.01$ or $\times 0.001$. For example, the frequency value of 50.01 Hz having the modulus of $\times 0.01$ will be received from the instrument as the whole number of 5001 . To process the value received from the instrument in this format, the value must be multiplied by the modulus. To write such a number to the instrument, the number must be divided by the modulus.

## Check sum

Arithmetic sum, calculated in a 2-byte word over fields \#2, \#3, \#4 and \#5 to produce a one-byte check sum in the range of 22 h to 7 Eh (hexadecimal) as follows: [ $\Sigma($ each byte $-22 \mathrm{H})$ ] mod $5 \mathrm{CH}+22 \mathrm{H}$

## Trailer

Two ASCII characters CR (ASCII 13) and LF (ASCII 10).

## NOTE

Fields \#3 and \#4 of the instrument response are always the same as those in the host request.

## Table 2-1 Specific ASCII Requests

| Message type |  | Description |  |
| :--- | :--- | :--- | :---: |
| Char | ASCII Hex |  |  |
| 0 | $30 h$ | Read basic data registers |  |
| 1 | 31 h | Read basic setup |  |
| 2 | $32 h$ | Write basic setup |  |
| 3 | $33 h$ | Read instrument status |  |
| 4 | $34 h$ | Reset/clear functions |  |
| 8 | $38 h$ | Reset the instrument |  |
| 9 | $39 h$ | Read version number |  |
| $?$ | $3 F h$ | Read extended status |  |
| B | $42 h$ | Read analog output allocation |  |
| b | $62 h$ | Write analog output allocation |  |
| D | $44 h$ | Read digital input allocation |  |
| d | $64 h$ | Write digital input allocation |  |
| G | $47 h$ | Read pulsing setpoint |  |
| g | $67 h$ | Write pulsing setpoint |  |
| H | $48 h$ | Read phase harmonics |  |
| 0 | $4 F h$ | Read Min/Max log |  |

Table 2-2 Direct Read/Write ASCII Requests

| Message type |  |  |
| :--- | :--- | :--- |
| Char | ASCII Hex |  |
| A | 41 h | Description |
| a | 61 h | Long-size direct read |
| X | 58 h | Variable-size direct write direct read |
| x | 78 h | Variable-size direct write |

## 3 EXCEPTION RESPONSES

The instrument will send the following error codes in the message body in response to incorrect host requests:

XK - the instrument is in programming mode
XM- invalid request type or illegal operation
XP - invalid data address or data value, or data is not available
NOTE
When a check or framing error is detected, the instrument will not act on or respond to the master's request.

## 4 SPECIFIC ASCII REQUESTS

### 4.1 Basic Data

Table 4-1 Read Request

| Message type (ASCII) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 |  |  |  |  |  |
| Message body (decimal) |  |  |  |  |  |
| Request - no body |  |  |  |  |  |
| Response |  |  |  |  |  |
| Field | Offset | Length | Parameter | Unit (2) | Range (1) |
| 1 | 0 | 4 | Voltage L1/L12 © | V/kV | 0 to Vmax |
| 2 | 4 | 4 | Voltage L2/L21 © | V/kV | 0 to Vmax |
| 3 | 8 | 4 | Voltage L3/L31 © | V/kV | 0 to Vmax |
| 4 | 12 | 5 | Current L1 | A | 0 to Imax |
| 5 | 17 | 5 | Current L2 | A | 0 to Imax |
| 6 | 22 | 5 | Current L3 | A | 0 to Imax |
| 7 | 27 | 6 | kW L1 | kW/MW | -Pmax to Pmax |
| 8 | 33 | 6 | kW L2 | kW/MW | -Pmax to Pmax |
| 9 | 39 | 6 | kW L3 | kW/MW | -Pmax to Pmax |
| 10 | 45 | 4 | Power factor L1 |  | -. 99 to 1.00 (4) |
| 11 | 49 | 4 | Power factor L2 |  | -. 99 to 1.00 (4) |
| 12 | 53 | 4 | Power factor L3 |  | -. 99 to 1.00 (4) |
| 13 | 57 | 6 | kW total | kW/MW | -Pmax to Pmax |
| 14 | 63 | 4 | Power factor total |  | -. 99 to 1.00 (4) |
| 15 | 67 | 6 | kWh import | MWh (3) | 0 to 99999. |
| 16 | 73 | 5 | Neutral (unbalanced) current | A | 0 to Imax |
| 17 | 78 | 4 | Frequency | Hz | 45.0 to 65.0 |
| 18 | 82 | 6 | kvar L1 | kvar/Mvar | -Pmax to Pmax |
| 19 | 88 | 6 | kvar L2 | kvar/Mvar | -Pmax to Pmax |
| 20 | 94 | 6 | kvar L3 | kvar/Mvar | -Pmax to Pmax |
| 21 | 100 | 6 | kVA L1 | kVA/MVA | 0 to Pmax |
| 22 | 106 | 6 | kVA L2 | kVA/MVA | 0 to Pmax |
| 23 | 112 | 6 | kVA L3 | kVA/MVA | 0 to Pmax |
| 24 | 118 | 6 | kvarh net | Mvarh (3) | -9999. to 99999. |
| 25 | 124 | 6 | kvar total | kvar/Mvar | -Pmax to Pmax |
| 26 | 130 | 6 | kVA total | kVA/MVA | 0 to Pmax |
| 27 | 136 | 6 | Maximum sliding window kW demand (5) | kW/MW | 0 to Pmax |
| 28 | 142 | 6 | Accum. kW demand | kW/MW | 0 to Pmax |
| 29 | 148 | 5 | Max. ampere demand L1 | A | 0 to Imax |
| 30 | 153 | 5 | Max. ampere demand L2 | A | 0 to Imax |
| 31 | 158 | 5 | Max. ampere demand L3 | A | 0 to Imax |
| 32 | 163 | 2 | Status inputs (hex) |  | See Table 4-13 |
| 33 | 165 | 6 | kWh export | MWh (3) | 0 to 99999. |
| 34 | 171 | 6 | Maximum sliding window kVA demand (5) | kVA/MVA | 0 to Pmax |
| 35 | 177 | 4 | Voltage THD L1/L12 | \% | 0.0 to 999. |
| 36 | 181 | 4 | Voltage THD L2/L23 | \% | 0.0 to 999. |
| 37 | 185 | 4 | Voltage THD L3 | \% | 0.0 to 999. |
| 38 | 189 | 4 | Current THD L1 | \% | 0.0 to 999. |
| 39 | 193 | 4 | Current THD L2 | \% | 0.0 to 999. |
| 40 | 197 | 4 | Current THD L3 | \% | 0.0 to 999. |
| 41 | 201 | 8 | kVAh | MVAh (3) | 0 to 99999.99 |
| 42 | 209 | 6 | Present sliding window kW demand (5) | kW/MW | 0 to Pmax |
| 43 | 215 | 6 | Present sliding window kVA demand (5) | kVA/MVA | 0 to Pmax |
| 44 | 221 | 4 | PF at maximum KVA demand |  | 0 to 1.00 |


| 45 | 225 | 4 | Current TDD L1 | 0.0 to 99.9 <br> 46 | 229 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 47 | 233 | 4 | 4 | Current TDD L2 | Current TDD L3 |

Fields indicated by an N/A mark are padded with ASCII zeros.
(1) The parameter limits are as follows:

Imax $(20 \%$ over-range $)=1.2 \times$ CT primary current [A]
Direct wiring (PT Ratio = 1):
Vmax (690 V input option) $=828.0 \mathrm{~V}$
Vmax ( 120 V input option ) $=144.0 \mathrm{~V}$
Pmax $=(\operatorname{Imax} \times \operatorname{Vmax} \times 3)$ [ $\mathrm{kW} \times 0.001$ ] if wiring mode is 4LN3 or 3LN3
Pmax $=(\operatorname{Imax} \times \operatorname{Vmax} \times 2)[\mathrm{kW} \times 0.001]$ if wiring mode is $4 \mathrm{LL} 3,30 \mathrm{P} 2,3$ DIR2, 3OP3 or 3LL3
Wiring via PTs (PT Ratio > 1):
Vmax (690 V input option) $=144 \times$ PT Ratio [V]
Vmax (120 V input option) $=144 \times$ PT Ratio [V]
Pmax $=(\operatorname{Imax} \times V \max \times 3) / 1000$ [MW $\times 0.001$ ] if wiring mode is $4 L N 3$ or 3LN3
Pmax $=(\operatorname{Imax} \times V \max \times 2) / 1000$ [MW $\times 0.001$ ] if wiring mode is 4LL3, 3OP2, 3DIR2, 3OP3 or 3LL3
(2) When ASCII compatibility mode is disabled (see Section 5.5), voltages, currents and powers are always transmitted with a decimal point at highest resolution available for the field. For direct wiring (PT Ratio $=1$ ), voltages are transmitted in volts, currents in amperes, and powers in kilowatts. For wiring via PT (PT Ratio > 1), voltages are transmitted in kilovolts, currents in amperes, and powers in megawatts. When the value is greater than the field width, the right most digits of the fractional part are truncated. For the best available resolution, see Note (2) to Table 5-7.
When ASCII compatibility mode is enabled, the C191HM provides a fully downward-compatible response using a lower resolution for voltages, currents and powers - the value is transmitted as a whole number until the field is filled up, and then it is converted to higher units and transmitted with a decimal point (when the value is greater than the field width, the right most digits of the fractional part will be truncated). Voltages are transmitted in volts as whole numbers or in kilovolts with a decimal point, currents in amperes as whole numbers, and powers in kilowatts as whole numbers or in megawatts with a decimal point.
(3) Energy readings are transmitted in MWh, Mvarh and MVAh units with a decimal point. If the energy value exceeds the field resolution, the right-most digits are truncated. The energy roll value is user selectable (see Section 5.4).
(4) For negative power factor, the minus sign is transmitted before a decimal point as shown in the table.
(5) To get block interval demand readings, set the number of demand periods equal to 1 (see Table 4-4).
(6) When the 4LN3 or 3LN3 wiring mode is selected, the voltages will be line-to-neutral; for any other wiring mode, they will be line-to-line voltages.

### 4.2 Basic Setup

Table 4-2 Read Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Message body (decimal) |  |  |  |  |
| Request |  |  |  |  |
| Parameter |  |  |  |  |
| Field | Offset | Length | Range |  |
| 1 | 0 | 3 | Parameter identifier | Response |
| Parameter |  |  |  |  |
| Field | Offset | Length | Pable 4-4 |  |
| 1 | 0 | 3 | Parameter identifier <br> Not used <br> Parameter value |  |
| 2 | 3 | 4 | Range |  |
| 3 | 7 | 6 | See Table 4-4 <br> Permanently set to 00.0 <br> See Table 4-4 |  |

Table 4-3 Write Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| 2 |  |  |  |  |
| Message body (decimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 3 | Parameter identifier <br> 2 | 3 |

Table 4-4 Basic Setup Parameters

| Parameter | Identifier | Range |
| :--- | :--- | :--- |
| Wiring mode (1) | W40 | $0=3 \mathrm{OP} 2,1=4 \mathrm{LN} 3,2=3 \mathrm{DIR2}$, |
|  |  | $3=4 \mathrm{LL} 3,4=3 \mathrm{OP} 3,5=3 \mathrm{LN} 3$, |
|  |  | $6=3 \mathrm{LL3}$ |
| PT ratio | U14 | 1.0 to 6500.0 |
| CT primary current | I17 | 1 to 6500 A |
| Power demand period | D11 | $1,2,5,10,15,20,30,60$ min |
|  |  | $255=$ external synchronization (2) |
| The number of demand periods | F47 | $1-15$ |
| Volt/ampere demand period | C12 | 0 to 1800 sec |
| Averaging buffer size | S41 | $8,16,32$ |
| Reset enable/disable | R42 | $0=$ disable, $1=$ enable |
| Nominal frequency | Q51 | 50,60 |
| Maximum demand load current | Q52 | 0 to $6,500 \mathrm{~A}(0=$ CT primary current $)$ |

(1) The wiring mode options are as follows:

3OP2 - 3-wire open delta using 2 CTs (2 element)
4LN3 - 4-wire WYE using 3 PTs (3 element), line to neutral voltage readings
3DIR2-3-wire direct connection using 2 CTs (2 element)
4LL3 - 4-wire WYE using 3 PTs (3 element), line to line voltage readings
3OP3-3-wire open delta using 3 CTs ( $21 / 2$ element)
3LN3 - 4-wire WYE using 2 PTs (2 1/2 element), line to neutral voltage readings
3LL3 - 4 -wire WYE using 2 PTs (2 $1 / 2$ element), line to line voltage readings
(2) Synchronization of power demand interval can be made through a digital input or via communications using the Synchronize power demand interval command (see Table 5-23)

### 4.3 Instrument Status

This request is supported only for compatibility with older instruments. It allows to read the status of the first four relays. To read the status of the all eight relays, use the extended status request (see Section 4.7) or extended data registers (see Section 5.2).

Table 4-5 Read Request

| Message type (ASCII) |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
| Message body (hexadecimal) |  |  |  |  |  |
| Request - no body |  |  |  |  |  |
| Response |  |  |  |  |  |
| Field | Offset | Length | Parameter | Range |  |
| 1 | 0 | 8 | Not used | 00000000 |  |
| 2 | 8 | 1 | Not used |  |  |
| 3 | 1 | Relay status | 0 |  |  |
| 3 | 1 | See Table 4-6 |  |  |  |

Table 4-6 Relay Status

| Bit | Description |
| :--- | :--- |
| 0 | Relay \#4 status |
| 1 | Relay \#3 status |
| 2 | Relay \#2 status |
| 3 | Relay \#1 status |

Bit meaning: $0=$ relay is energized, $1=$ relay is not energized

### 4.4 Reset/Clear Functions

These operations can be also performed by using the direct write requests instead of the specific request '4' (see Section 5.11).

Table 4-7 Write Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Message body (hexadecimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 1 | Reset function <br> Target | See Table 4-8 <br> See Table 4-8 (the field can be <br>  <br> 2 |

## Table 4-8 Reset/Clear Functions

| Function | Description | Target |
| :--- | :--- | :--- |
| 1 | Clear total energy registers | 0 |
| 2 | Clear total maximum demand registers | $0=$ all maximum demands |
|  |  | $1=$ power demands |
| $3-4$ | Reserved | $2=$ volt/ampere demands |
| 5 | Clear event/time counters | $0=$ all counters |
| 6 | Clear Min/Max log | $1-4=$ counter \#1-\#4 |
| $7-F$ | Reserved | 0 |

### 4.5 Reset the Instrument (warm restart)

This request causes the instrument to perform full reset and restart, the same as when the instrument is turned on. No response is expected.

Table 4-9 Write Request

| Message type (ASCII) |
| :---: |
| $\mathbf{8}$ |
| Message body |
| Request - no body |
| Response - no response |

### 4.6 Read Firmware Version Number

Table 4-10 Read Request

| Message type (ASCII) |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: |
| Message body (decimal) |  |  |  |  |  |  |
| Request - no body |  |  |  |  |  |  |
| Response |  |  |  |  |  |  |
| Parameter |  |  |  |  |  | Range |
| Field | Offset | Length | Prer |  |  |  |
| 1 | 0 | 3 | Firmware version | $300-399$ |  |  |

### 4.7 Extended Instrument Status

Table 4-11 Read Request

| Message type (ASCII) |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
| Message body (hexadecimal) |  |  |  |  |  |
| Request - no body |  |  |  |  |  |
| Response |  |  |  |  |  |
| Field | Offset | Length | Parameter | Range |  |
| 1 | 0 | 4 | Relay status | See Table 4-12 |  |
| 2 | 4 | 4 | Not used | 0 |  |
| 3 | 8 | 4 | Status inputs | See Table 4-13 |  |
| 4 | 12 | 4 | Setpoints status | See Table 4-14 |  |
| 5 | 16 | 4 | Log status | See Table 4-15 |  |
| 6 | 20 | 36 | Not used | 0 |  |

Table 4-12 Relay Status

| Bit | Description |
| :--- | :--- |
| 0 | Relay \#1 status |
| 1 | Relay \#2 status |
| 2 | Relay \#3 status |
| 3 | Relay \#4 status |
| 4 | Relay \#5 status |
| 5 | Relay \#6 status |
| 6 | Relay \#7 status |
| 7 | Relay \#8 status |
| $8-15$ | Not used (permanently set to 0) |

Bit meaning: $0=$ relay is not energized, $1=$ relay is energized
Table 4-13 Status Inputs

| Bit | Description |
| :--- | :--- |
| 0 | Status input |
| $1-15$ | Not used (permanently set to 0) |

Bit meaning: $0=$ contact open, $1=$ contact closed

## Table 4-14 Setpoints Status

| Bit | Description |
| :--- | :--- |
| 0 | Setpoint \# 1 status |
| 1 | Setpoint \# 2 status |
| 2 | Setpoint \# 3 status |
| 3 | Setpoint \# 4 status |
| 4 | Setpoint \# 5 status |
| 5 | Setpoit \# 6 status |
| 6 | Setpoint \# 7 status |
| 7 | Setpoint \# 8 status |
| 8 | Setpoint \# 9 status |
| 9 | Setpoint \# 10 status |
| 10 | Setpoint \# 11 status |
| 11 | Setpoint \# 12 status |
| 12 | Setpoint \# 13 status |
| 13 | Setpoint \# 14 status |
| 14 | Setpoint \# 15 status |
| 15 | Setpoint \# 16 status |

Bit meaning: $0=$ setpoint is released, $1=$ setpoint is operated
Table 4-15 Log Status

| Bit | Description |
| :--- | :--- |
| 0 | Reserved |
| 1 | New Min/Max log |
| $2-15$ | Not used (permanently set to 0) |

Bit meaning: $0=$ no new logs, $1=$ new log recorded (the new log flag is reset when the user reads the first log record after the flag has been set)

### 4.8 Analog Output Allocation

Table 4-16 Read Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| B |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 2 | Analog channel number | Response |
| Parameter |  |  |  |  |
| Field | Offset | Length | Range |  |
| 1 | 0 | 2 | Analog channel number |  |
| 2 | 2 | 4 | Output parameter index <br> Zero scale (0/4 mA) <br> 3 | 6 |
| 14 | 8 | Full scale (20 mA) | 0 |  |
| 4 | 8 | See Table 4-18 |  |  |

Table 4-17 Write Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| b Message body (hexadecimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Parameter |  |  |  |  |
| Field | Offset | Length |  |  |
| 1 | 0 | 2 | Analog channel number | Range |
| 2 | 2 | 4 | Output parameter index | 0 |
| 3 | 6 | 8 | Zero scale (0/4 mA) | See Table 4-18 |
| 4 | 14 | 8 | Full scale (20 mA) | See Table 4-18 |

Except for the signed power factor (see Note 3 to Table 4-18), the output scale is linear within the value range. The scale range will be inverted if the full scale specified is less than the zero scale.

Table 4-18 Analog Output Parameters

| Parameter | Data index | Length | Unit (2) | Scale range ${ }^{(1)}$ |
| :---: | :---: | :---: | :---: | :---: |
| None |  |  |  |  |
| None | 0000h | 4 |  | 0 |
| Real-time values per phase |  |  |  |  |
| Voltage L1/L12 (5) | 0C00h | 8 | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 0C01h | 8 | $0.1 \mathrm{~V} / 1 \mathrm{~V}$ | 0 to Vmax |
| Voltage L3/L31 (5) | 0C02h | 8 | 0.1V/1V | 0 to Vmax |
| Current L1 | 0C03h | 8 | 0.01A | 0 to Imax |
| Current L2 | 0C04h | 8 | 0.01A | 0 to Imax |
| Current L3 | 0C05h | 8 | 0.01A | 0 to Imax |
| Real-time total value |  |  |  |  |
| Total kW | OFOOh | 8 | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 0F01h | 8 | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | OF02h | 8 | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF (4) | 0F03h | 4 | 0.001 | -999 to 1000 |
| Total PF Lag | 0F04h | 4 | 0.001 | -999 to 1000 |
| Total PF Lead | 0F05h | 4 | 0.001 | -999 to 1000 |
| Real-time auxiliary values |  |  |  |  |
| Frequency (3) | 1002h | 4 | 0.01 Hz | 0 to 10000 |
| Average values per phase |  |  |  |  |
| Voltage L1/L12 (5) | 1100h | 8 | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 1101h | 8 | $0.1 \mathrm{~V} / 1 \mathrm{~V}$ | 0 to Vmax |
| Voltage L3/L31 (5) | 1102h | 8 | 0.1V/1V | 0 to Vmax |
| Current L1 | 1103h | 8 | 0.01A | 0 to Imax |
| Current L2 | 1104h | 8 | 0.01A | 0 to Imax |
| Current L3 | 1105h | 8 | 0.01A | 0 to Imax |
| Average total values |  |  |  |  |
| Total kW | 1400h | 8 | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 1401h | 8 | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 1402h | 8 | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF (4) | 1403h | 4 | 0.001 | -999 to 1000 |
| Total PF Lag | 1404h | 4 | 0.001 | -999 to 1000 |
| Total PF Lead | 1405h | 4 | 0.001 | -999 to 1000 |
| Average auxiliary values |  |  |  |  |
| Neutral current | 1501h | 8 | 0.01A | 0 to Imax |
| Frequency (3) | 1502h | 4 | 0.01 Hz | 0 to 10000 |
| Present demands |  |  |  |  |
| Accumulated kW demand (import) | 160Fh | 8 | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Accumulated kVA demand | 1611h | 8 | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |

(1) For parameter limits, see Note (1) to Table 4-1.
(2) When using direct wiring (PT Ratio $=1$ ), voltages are transmitted in 0.1 V units, currents in 0.01 A units, and powers in $0.001 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units. For wiring via PTs (PT Ratio > 1), voltages are transmitted in 1 V units, currents in 0.01 A units, and powers in $1 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units.
(3) The actual frequency range is 45.00 to 65.00 Hz
(4) The output scale for signed (bi-directional) power factor is symmetrical with regard to $\pm 1.000$ and is linear from -0 to -1.000 , and from 1.000 to +0 (note that $-1.000 \equiv+1.000$ ). Negative power factor is output as $[-1.000$ minus measured value], and non-negative power factor is output as $[+1.000$ minus measured value]. To define the entire range for power factor from -0 to +0 , the scales would be specified as $-0 / 0$. Because of the fact that negative zero may not be transmitted, the value of -0.001 is used to specify the scale of -0 , and both +0.001 and 0.000 are used to specify the scale of +0 . To define the range of -0 to 0 , you must send $-1 / 1$ or $-1 / 0$ (considering the modulus of $\times 0.001$ ).
(5) When the 4LN3 or 3LN3 wiring mode is selected, the voltages will be line-to-neutral; for any other wiring mode, they will be line-to-line voltages.

### 4.9 Digital Input Allocation

Table 4-19 Read Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Parameter |  |  |  |  |
| Field | Offset | Length | Range |  |
| 1 | 0 | 2 | Digital input group ID | Response |
| Parameter |  |  |  |  |
| Field | Offset | Length | Pable 4-21 |  |
| 1 | 0 | 2 |  |  |
| 2 | 2 | Digital input group ID <br> Allocation mask | See Table 4-21 <br> See Table 4-22 |  |

Table 4-20 Write Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Message body (hexadecimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Pength |  |  |  |  |

Table 4-21 Digital Input Groups

| Group ID | Description |
| :--- | :--- |
| 0 | Status inputs (1) |
| 1 | Pulse inputs (1) |
| 2 | Not used (read as 0) © |
| 3 | External synchronization pulse input |

(1) Writing to these locations is ignored. No error will occur.

## NOTE

When a digital input is allocated for the external synchronization pulse, it is automatically configured as a pulse input, otherwise it is configured as a status input.

Table 4-22 Digital Inputs Allocation Mask

| Bit number | Description |
| :--- | :--- |
| 0 | Digital input allocation status |
| $1-15$ | Not used |

Bit meaning: $0=$ input not allocated, $1=$ input allocated to the group

### 4.10 Pulsing Setpoints

Table 4-23 Read Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| G |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 2 | Pulse output ID | 0-7 (see Table 4-25) |
| Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| $\begin{array}{\|l} \hline 1 \\ 2 \\ 3 \end{array}$ | 0 2 4 | $\begin{aligned} & 2 \\ & 2 \\ & 4 \end{aligned}$ | Pulse output ID Output parameter ID For energy pulsing = number of unit-hours per pulse, otherwise - permanently set to 0 | $\begin{aligned} & 0-7 \text { (see Table 4-25) } \\ & \text { See Table 4-26 } \\ & 0-9999 \end{aligned}$ |

Table 4-24 Write Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| g |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 2 | Pulse output ID | 0-7 (see Table 4-25) |
| 2 | 2 | 2 | Output parameter ID | See Table 4-26 |
| 3 | 4 | 4 | For energy pulsing = number of unithours per pulse, otherwise - set to 0 | 0-9999 |

## Table 4-25 Pulse Outputs

| Pulsing output ID | Output allocation |
| :--- | :--- |
| 0 | Relay \#1 |
| 1 | Relay \#2 |
| 2 | Relay \#3 |
| 3 | Relay \#4 |
| 4 | Relay \#5 |
| 5 | Relay \#6 |
| 6 | Relay \#7 |
| 7 | Relay \#8 |

Table 4-26 Pulsing Output Parameters

| Pulsing parameter ID | Identifier |
| :--- | :--- |
| None | 0 |
| kWh import | 1 |
| kWh export | 2 |
| kvarh import | 4 |
| kvarh export | 5 |
| kvarh total (absolute) | 6 |
| kVAh total | 7 |

### 4.11 Min/Max Log

The Min/Max log read request is supported only for compatibility with other models of instruments. Because the Min/Max log is not time stamped in the C191HM, this request yields only the Min/Max log parameters which can be read directly via extended data registers (see Table 5-7).

Table 4-27 Read Request

| Message type (ASCII) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 |  |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |  |
| Request |  |  |  |  |  |
| Field | Offset | Length | Parameter |  | Range |
| 1 | 0 | 4 | Start Min/Max parameter ID |  | See Table 5-7 |
| 2 | 4 | 2 | The number of subsequent parameters to read |  | 1-12 |
| Response |  |  |  |  |  |
| Field | Offset | Length | Parameter |  | Range |
| 1 | 0 | 2 | The number of parameters in message |  | 1-12 |
| 2 | 2 | 2 | Log parameter \#1 | Second | 0 |
| 3 | 4 | 2 |  | Minute | 0 |
| 4 | 6 | 2 |  | Hour | 0 |
| 5 | 8 | 2 |  | Day | 0 |
| 6 | 10 | 2 |  | Month | 0 |
| 7 | 12 | 2 |  | Year | 0 |
| 8 | 14 | 8 |  | Parameter value | See Table 5-7 |
| 9 | 22 | 2 | Log parameter \#2 | Second | 0 |
| 10 | 24 | 2 |  | Minute | 0 |
| 11 | 26 | 2 |  | Hour | 0 |
| 12 | 28 | 2 |  | Day | 0 |
| 13 | 30 | 2 |  | Month | 0 |
| 14 | 32 | 2 |  | Year |  |
| 15 | 34 | 8 |  | Parameter value | See Table 5-7 |
| . . . |  |  |  |  |  |
| 79 | 222 | 2 | Log parameter \#12 | Second | 0 |
| 80 | 224 | 2 |  | Minute | 0 |
| 81 | 226 | 2 |  | Hour | 0 |
| 82 | 228 | 2 |  | Day | 0 |
| 83 | 230 | 2 |  | Month | 0 |
| 84 | 232 | 2 |  | Year | 0 |
| 85 | 234 | 8 |  | Parameter value | See Table 5-7 |

This request allows you to obtain the Min/Max log parameters. Up to 12 parameters can be read in one packet from a single parameter group. The available Min/Max log parameters are listed in Table 5-7. The time stamp is not available in the C191HM and is padded with zeros.

### 4.12 Phase Harmonics

Table 4-28 Read Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| H |  |  |  |  |
| Message body (decimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 1 | Channel ID | 1-6 (see Table 4-29) |
| Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 5 | RMS value for the channel (2, V/A | 0 to Vmax①/Imax |
| 2 | 5 | 5 | Fundamental frequency | 0 to 65.50 |
| 3 | 10 | 5 | \% THD | 0.0 to 100.0 |
| 4 | 15 | 5 | Harmonic H01 (reference) | 100.0 |
| 5 | 20 | 5 | Harmonic H02 | 0.00 to 100.0 |
| 6 | 25 | 5 | Harmonic H03 | 0.00 to 100.0 |
| 43 | 210 | 5 | Harmonic H40 | 0.00 to 100.0 |

(1) Phase voltage will be line-to-line voltage in 3OP2 and 3OP3 wiring modes, and line-to-neutral voltage in other configurations.
(2) For RMS value representation, see Note (2) to Table 4-1.

Table 4-29 Harmonic Spectrum Channels

| Channel ID | Description |
| :--- | :--- |
| 1 | Voltage L1/L12 |
| 2 | Voltage L2/L23 |
| 3 | Voltage L3 |
| 4 | Current L1 |
| 5 | Current L2 |
| 6 | Current L3 |

## 5 DIRECT READ/WRITE REQUESTS

### 5.1 General

This chapter describes the instrument data locations that are addressed directly using data location indexes. These locations can be accessed by using universal direct read/write requests instead of specific ASCII requests. A data index is a 4-digit hexadecimal number, which actually comprises a two-digit data group identifier followed by a two-digit location offset within a group. All data are transmitted in ASCII hexadecimal notation. Negative numbers are transmitted in 2-complement code.

### 5.1.1 Long-Size Direct Read/Write

Table 5-1 Read Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| A |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 4 | Start data index to read | 0000h - FFFFh |
| 2 | 4 | 2 | The number of contiguous data items to read | 1-30 (01h-1Eh) |
| Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 2 | Number of data items in the message | 1-30 (01h-1Eh) |
| 2 | 2 | 8 | Data \#1 value |  |
| 3 | 10 | 8 | Data \#2 value |  |
| $\ldots$ | $\ldots$ | $\ldots$ | $\cdots$ |  |
| 31 | 234 | 8 | Data \#30 value |  |

Table 5-2 Write Request

| Message type (ASCII) |  |  |  |  |
| :--- | :--- | :--- | :--- | :---: |
| a Message body (hexadecimal) |  |  |  |  |
| Request/ Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 4 | Data index to write | 0000 h - FFFFh |
| 2 | 4 | 8 | Data value to write |  |

In long-size direct read/write messages, all data items are read and written as long signed integers, which are represented in messages by 8 -digit hexadecimal numbers, regardless of the actual data size.

By using a long-size direct read request, up to 30 contiguous parameters can be read at once. A write request allows for writing only one data location at a time.

### 5.1.2 Variable-Size Direct Read/Write

Table 5-3 Read Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| X |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 4 | Start data index to read | 0000h - FFFFh |
| 2 | 4 | 2 | The number of contiguous data items to read | 1-61 (01h-3Dh) |
| Response |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 2 | Number of data items in the message | 1-61 (01h - 3Dh) |
| 2 | 2 | 2/4/8 | Data \#1 value |  |
| 3 |  | 2/4/8 | Data \#2 value |  |
| $\ldots$ | $\ldots$ | 2/4/8/8 | Data \#60 value |  |

Table 5-4 Write Request

| Message type (ASCII) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\mathbf{x}$ |  |  |  |  |
| Message body (hexadecimal) |  |  |  |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 4 | Start data index to write | 0000h - FFFFh |
| 2 | 4 | 2 | The number of contiguous data items to write | 1-61 (01h-3Dh) |
| 2 | 2 | 2/4/8 | Data \#1 value |  |
| 3 |  | 2/4/8 | Data \#2 value |  |
| $\ldots$ | $\ldots$ | 2/4/8 | Data \#60 value |  |
| Request |  |  |  |  |
| Field | Offset | Length | Parameter | Range |
| 1 | 0 | 4 | Start data index written | 0000h - FFFFh |
| 2 | 4 | 2 | The number of data items written | 1-61 (01h-3Dh) |

With variable-size direct read/write messages, data items are read and written as 2,4 or 8 -character hexadecimal numbers. The actual data size is indicated for each data location. When written, the data format should be exactly the same as indicated.

The number of parameters that can be read or written by a single read/write request depends on the size of each data item. The total length of all parameters should not exceed 240 characters.

### 5.1.3 User Assignable Registers

The instrument contains 120 user assignable registers in the range of indexes 8000 h to 8077 h (see Table $5-5)$. You can map any of these registers to either register index, accessible in the instrument through direct read/write requests. Registers that reside in different locations may be accessed by a single request by re-mapping them to adjacent addresses in the user assignable registers area.

The actual indexes of the user assignable registers which are accessed via indexes 8000h to 8077h are specified in the user assignable register map. It occupies indexes 8100h to 8177h (see Table 5-6), where the map register 8100 h should contain the actual index of the register accessed via assignable register 8000h, register 8101 h should contain the actual index of the register accessed via assignable register 8001h, and so on. Note that the user assignable register indexes and the user register map indexes may not be re-mapped.

Table 5-5 User Assignable Registers

| Data index <br> (hex) | Register contents | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| 8000 h | User definable data 0 | (1) | (1) | (1) |
| 8001 h | User definable data 1 | (1) | (1) | (1) |
| 8002 h | User definable data 2 | $\ldots$ | $(1)$ | (1) |
| $\ldots$ | $\ldots$ | (1) | (1) |  |
| 8077 h | User definable data 119 |  |  |  |

(1) - depends on the mapped register

Table 5-6 User Assignable Register Map

| Data index <br> (hex) | Register contents | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| 8100 h | Data index for user data 0 | 4 | R/W | $0000 \mathrm{~h}-\mathrm{FFFFh}$ |
| 8101 h | Data index for user data 1 | 4 | R/W | $0000 \mathrm{~h}-\mathrm{FFFFh}$ |
| 8102 h | Data index for user data 2 | 4 | R/W | $0000 \mathrm{~h}-\mathrm{FFFFh}$ |
| $\ldots$ | $\ldots$ | $\ldots$ |  |  |
| 8177 h | Data index for user data 119 | 4 | R/W | $0000 \mathrm{~h}-\mathrm{FFFFh}$ |

To build your own register map, write to map registers (8100h to 8177h) the actual addresses you want to read from or write to via the assignable area ( 8000 h to 8077 h ). For example, if you want to read registers 0C00h (real-time voltage of phase A) and 1700h (kWh import) via indexes 8000h-8001h, do the following:

- write 0C00h to register 8100 h
- write 1700h to register 8101h

Reading from registers $8000 \mathrm{~h}-8001 \mathrm{~h}$ will return the voltage reading in register 8000 h , and the kWh reading in register 8001h.

### 5.2 Extended Data Registers

Table 5-7 Extended Data Table

| Parameter | Data index | Length | Direction | Unit | Range (1) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| None |  |  |  |  |  |
| None | 0000h | 4 | R |  | 0 |
| Status inputs |  |  |  |  |  |
| Status inputs | 0600h | 4 | R |  | See Table 4-13 |
| Relays |  |  |  |  |  |
| Relay status | 0800h | 4 | R |  | See Table 4-12 |
| Event/ time counters |  |  |  |  |  |
| Pulse counter \#1 | 0A00h | 8 | R/W |  | 0 to 99999 |
| Pulse counter \#2 | 0A01h | 8 | R/W |  | 0 to 99999 |
| Pulse counter \#3 | 0A02h | 8 | R/W |  | 0 to 99999 |
| Pulse counter \#4 | 0A03h | 8 | R/W |  | 0 to 99999 |
| Real-time values per phase |  |  |  |  |  |
| Voltage L1/L12 (5) | 0C00h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 0C01h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L3/L31 (5) | 0C02h | 8 | R | 0.1V/1V | 0 to Vmax |
| Current L1 | 0C03h | 8 | R | 0.01A | 0 to Imax |
| Current L2 | 0C04h | 8 | R | 0.01A | 0 to Imax |
| Current L3 | 0C05h | 8 | R | 0.01A | 0 to Imax |
| kW L1 | 0C06h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L2 | 0C07h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L3 | 0C08h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kvar L1 | 0C09h | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kvar L2 | 0C0Ah | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kvar L3 | OCOBh | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kVA L1 | OCOCh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L2 | 0C0Dh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L3 | OCOEh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |


| Parameter | Data index | Length | Direction | Unit | Range (1) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power factor L1 | OCOFh | 4 | R | 0.001 | -999 to 1000 |
| Power factor L2 | 0C10h | 4 | R | 0.001 | -999 to 1000 |
| Power factor L3 | 0C11h | 4 | R | 0.001 | -999 to 1000 |
| Voltage THD L1/L12 | 0C12h | 4 | R | 0.1\% | 0 to 9999 |
| Voltage THD L2/L23 | 0C13h | 4 | R | 0.1\% | 0 to 9999 |
| Voltage THD L3 | 0C14h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L1 | 0C15h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L2 | 0C16h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L3 | 0C17h | 4 | R | 0.1\% | 0 to 9999 |
| K-Factor L1 | 0C18h | 4 | R | 0.1 | 10 to 9999 |
| K-Factor L2 | 0C19h | 4 | R | 0.1 | 10 to 9999 |
| K-Factor L3 | 0C1Ah | 4 | R | 0.1 | 10 to 9999 |
| Current TDD L1 | 0C1Bh | 4 | R | 0.1\% | 0 to 1000 |
| Current TDD L2 | 0C1Ch | 4 | R | 0.1\% | 0 to 1000 |
| Current TDD L3 | 0C1Dh | 4 | R | 0.1\% | 0 to 1000 |
| Voltage L12 | 0C1Eh | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L23 | 0C1Fh | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L31 | 0C20h | 8 | R | 0.1V/1V | 0 to Vmax |
| Real-time total values |  |  |  |  |  |
| Total kW | OFOOh | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | OF01h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 0F02h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF | 0F03h | 4 | R | 0.001 | -999 to 1000 |
| Reserved | 0F04h | 4 | R |  |  |
| Reserved | OF05h | 4 | R |  | 0 |
| Real-time auxiliary values |  |  |  |  |  |
| Reserved | 1000h | 8 | R |  | 0 |
| Neutral current | 1001h | 8 | R | 0.01A | 0 to Imax |
| Frequency (4) | 1002h | 4 | R | 0.01 Hz | 0 to 10000 |
| Voltage unbalance | 1003h | 4 | R | 1\% | 0 to 300 |
| Current unbalance | 1004h | 4 | R | 1\% | 0 to 300 |
| Average values per phase |  |  |  |  |  |
| Voltage L1/L12 (5) | 1100h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 1101h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L3/L31 (5) | 1102h | 8 | R | 0.1V/1V | 0 to Vmax |
| Current L1 | 1103h | 8 | R | 0.01A | 0 to Imax |
| Current L2 | 1104h | 8 | R | 0.01A | 0 to Imax |
| Current L3 | 1105h | 8 | R | 0.01A | 0 to Imax |
| kW L1 | 1106h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L2 | 1107h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L3 | 1108h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kvar L1 | 1109h | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kvar L2 | 110Ah | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| kvar L3 | 110Bh | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| kVA L1 | 110Ch | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L2 | 110Dh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L3 | 110Eh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Power factor L1 | 110Fh | 4 | R | 0.001 | -999 to 1000 |
| Power factor L2 | 1110h | 4 | R | 0.001 | -999 to 1000 |
| Power factor L3 | 1111h | 4 | R | 0.001 | -999 to 1000 |
| Voltage THD L1/L12 | 1112h | 4 | R | 0.1\% | 0 to 9999 |
| Voltage THD L2/L23 | 1113h | 4 | R | 0.1\% | 0 to 9999 |
| Voltage THD L3 | 1114h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L1 | 1115h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L2 | 1116h | 4 | R | 0.1\% | 0 to 9999 |
| Current THD L3 | 1117h | 4 | R | 0.1\% | 0 to 9999 |
| K-Factor L1 | 1118h | 4 | R | 0.1 | 10 to 9999 |
| K-Factor L2 | 1119h | 4 | R | 0.1 | 10 to 9999 |
| K-Factor L3 | 111Ah | 4 | R | 0.1 | 10 to 9999 |
| Current TDD L1 | 111Bh | 4 | R | 0.1\% | 0 to 1000 |
| Current TDD L2 | 111Ch | 4 | R | 0.1\% | 0 to 1000 |
| Current TDD L3 | 111Dh | 4 | R | 0.1\% | 0 to 1000 |
| Voltage L12 | 110Eh | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L23 | 110Fh | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L31 | 1120h | 8 | R | 0.1V/1V | 0 to Vmax |


| Parameter | Data index | Length | Direction | Unit | Range (1) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Average total values |  |  |  |  |  |
| Total kW | 1400h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 1401h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 1402h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF | 1403h | 4 | R | 0.001 | -999 to 1000 |
| Reserved | 1404h | 4 | R |  |  |
| Reserved | 1405h | 4 | R |  | 0 |
| Average auxiliary values |  |  |  |  |  |
| Reserved | 1500h | 8 | R |  | 0 |
| Neutral current | 1501h | 8 | R | 0.01A | 0 to Imax |
| Frequency (4) | 1502h | 4 | R | 0.01 Hz | 0 to 10000 |
| Voltage unbalance | 1503h | 4 | R | 1\% | 0 to 300 |
| Current unbalance | 1504h | 4 | R | 1\% | 0 to 300 |
| Present demands |  |  |  |  |  |
| Volt demand L1/L12 (5) | 1600h | 8 | R | 0.1V/1V | 0 to Vmax |
| Volt demand L2/L23 (5) | 1601h | 8 | R | 0.1V/1V | 0 to Vmax |
| Volt demand L3/L31 5 | 1602h | 8 | R | 0.1V/1V | 0 to Vmax |
| Ampere demand L1 | 1603h | 8 | R | 0.01A | 0 to Imax |
| Ampere demand L2 | 1604h | 8 | R | 0.01A | 0 to Imax |
| Ampere demand L3 | 1605h | 8 | R | 0.01A | 0 to Imax |
| Block kW demand | 1606h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Reserved | 1607h | 8 | R |  |  |
| Block kVA demand | 1608h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Sliding window kW demand | 1609h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Reserved | 160Ah | 8 | R |  |  |
| Sliding window kVA demand | 160Bh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Reserved | 160Ch | 8 | R |  | 0 |
| Reserved | 160Dh | 8 | R |  | 0 |
| Reserved | 160Eh | 8 | R |  |  |
| Accumulated kW demand | 160Fh | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Reserved | 1610h | 8 | R |  |  |
| Accumulated kVA demand | 1611h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Predicted sliding window kW demand | 1612h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Reserved | 1613h | 8 | R |  |  |
| Predicted sliding window kVA demand | 1614h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| PF at maximum sliding window kVA demand | 1615h | 4 | R | 0.001 | 0 to 1000 |
| Total energies |  |  |  |  |  |
| kWh import | 1700h | 8 | R | kWh | 0 to 108-1 |
| kWh export | 1701h | 8 | R | kWh | 0 to 108-1 |
| Reserved | 1702h | 8 | R |  |  |
| Reserved | 1703h | 8 | R |  |  |
| kvarh import | 1704h | 8 | R | kvarh | 0 to 108-1 |
| kvarh export | 1705h | 8 | R | kvarh | 0 to 108-1 |
| Reserved | 1706h | 8 | R |  |  |
| Reserved | 1707h | 8 | R |  |  |
| kVAh total | 1708h | 8 | R | kVAh | 0 to 108-1 |
| Phase energies |  |  |  |  |  |
| kWh import L1 | 1800h | 8 | R | kWh | 0 to 108-1 |
| kWh import L2 | 1801h | 8 | R | kWh | 0 to 108-1 |
| kWh import L3 | 1802h | 8 | R | kWh | 0 to 108-1 |
| kvarh import (inductive) L1 | 1803h | 8 | R | kvarh | 0 to 108-1 |
| kvarh import (inductive) L2 | 1804h | 8 | R | kvarh | 0 to 108-1 |
| kvarh import (inductive) L3 | 1805h | 8 | R | kvarh | 0 to 108-1 |
| kVAh L1 | 1806h | 8 | R | kVAh | 0 to 108-1 |
| kVAh L2 | 1807h | 8 | R | kVAh | 0 to 108-1 |
| kVAh L3 | 1808h | 8 | R | kVAh | 0 to 108-1 |
| L1/ L12 phase voltage harmonics |  |  |  |  |  |
| Harmonic H01 | 1900h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1901h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | 1927h | 4 | R | 0.01\% | 0 to 10000 |


| Parameter | Data index | Length | Direction | Unit | Range (1) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L2/ L23 phase voltage harmonics |  |  |  |  |  |
| Harmonic H01 | 1A00h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1A01h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | $\cdots \mathrm{B}$ - 27 h | 4 | R | 0.01\% | 0 to 10000 |
| L3 phase voltage harmonics |  |  |  |  |  |
| Harmonic H01 | 1B00h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1B01h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | 1B27h | 4 | R | 0.01\% | 0 to 10000 |
| L1 phase current harmonics |  |  |  |  |  |
| Harmonic H01 | 1C00h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1C01h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | $\cdots$ | 4 | R | 0.01\% | 0 to 10000 |
| L2 phase current harmonics |  |  |  |  |  |
| Harmonic H01 | 1D00h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1D01h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | - 1 D27h |  | R | 0.01\% | 0 to 10000 |
| L3 phase current harmonics |  |  |  |  |  |
| Harmonic H01 | 1E00h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H02 | 1E01h | 4 | R | 0.01\% | 0 to 10000 |
| Harmonic H40 | 1E27h | 4 | R | 0.01\% | 0 to 10000 |
| Fundamental's (H01) real-time values per phase |  |  |  |  |  |
| Voltage L1/L12 | 2900h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 | 2901h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L3/L31 | 2902h | 8 | R | 0.1V/1V | 0 to Vmax |
| Current L1 | 2903h | 8 | R | 0.01A | 0 to Imax |
| Current L2 | 2904h | 8 | R | 0.01A | 0 to Imax |
| Current L3 | 2905h | 8 | R | 0.01A | 0 to Imax |
| kW L1 | 2906h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L2 | 2907h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kW L3 | 2908h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| kvar L1 | 2909h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| kvar L2 | 290Ah | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kvar L3 | 290Bh | 8 | R | 0.001kvar/1kvar | -Pmax to Pmax |
| kVA L1 | 290Ch | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L2 | 290Dh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| kVA L3 | 290Eh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Power factor L1 | 290Fh | 4 | R | 0.001 | -999 to 1000 |
| Power factor L2 | 2910h | 4 | R | 0.001 | -999 to 1000 |
| Power factor L3 | 2911h | 4 | R | 0.001 | -999 to 1000 |
| Fundamental's (H01) real-time total values |  |  |  |  |  |
| Total kW | 2a00h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 2a01h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 2a02h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF | 2a03h | 4 | R | 0.001 | -999 to 1000 |
| Minimum real-time values per phase (M) |  |  |  |  |  |
| Voltage L1/L12 (5) | 2C00h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 2C01h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L3/L31 © | 2C02h | 8 | R | 0.1V/1V | 0 to Vmax |
| Current L1 | 2C03h | 8 | R | 0.01A | 0 to Imax |
| Current L2 | 2C04h | 8 | R | 0.01A | 0 to Imax |
| Current L3 | 2C05h | 8 | R | 0.01A | 0 to Imax |
| Minimum real-time total values ( M ) |  |  |  |  |  |
| Total kW | 2D00h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 2D01h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 2D02h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF (3) | 2D03h | 4 | R | 0.001 | 0 to 1000 |
| Minimum real-time auxiliary values (M) |  |  |  |  |  |
| Reserved Neutral current | $\begin{array}{\|l\|l\|} \hline \text { 2E00h } \\ \text { 2E01h } \end{array}$ | $\begin{array}{\|l} 8 \\ 8 \end{array}$ | $\begin{aligned} & \hline R \\ & R \end{aligned}$ | 0.01A | $\begin{aligned} & 0 \\ & 0 \text { to Imax } \end{aligned}$ |


| Parameter | Data index | Length | Direction | Unit | Range (1) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Frequency (4) | 2E02h | 4 | R | 0.01 Hz | 0 to 10000 |
| Minimum demands ( $\mathbf{M}^{\text {) - Reserved }}$ |  |  |  |  |  |
| Reserved | $\begin{aligned} & \text { 2F00h- } \\ & \text { 2FOBh } \\ & \hline \end{aligned}$ | 8 | R |  | 0 |
| Maximum real-time values per phase (M) |  |  |  |  |  |
| Voltage L1/L12 (5) | 3400h | 8 | R | 0.1V/1V | 0 to Vmax |
| Voltage L2/L23 (5) | 3401h | 8 | R | $0.1 \mathrm{~V} / 1 \mathrm{~V}$ | 0 to Vmax |
| Voltage L3/L31 (5) | 3402h | 8 | R | 0.1V/1V | 0 to Vmax |
| Current L1 | 3403h | 8 | R | 0.01A | 0 to Imax |
| Current L2 | 3404h | 8 | R | 0.01A | 0 to Imax |
| Current L3 | 3405h | 8 | R | 0.01A | 0 to Imax |
| Maximum real-time total values (M) |  |  |  |  |  |
| Total kW | 3500h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | -Pmax to Pmax |
| Total kvar | 3501h | 8 | R | $0.001 \mathrm{kvar} / 1 \mathrm{kvar}$ | -Pmax to Pmax |
| Total kVA | 3502h | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Total PF (3) | 3503h | 4 | R | 0.001 | 0 to 1000 |
| Maximum real-time auxiliary values (M) |  |  |  |  |  |
| Reserved | 3600h | 8 | R |  | 0 |
| Neutral current | 3601h | 8 | R | 0.01A | 0 to Imax |
| Frequency (4) | 3602h | 4 | R | 0.01 Hz | 0 to 10000 |
| Maximum demands (M) |  |  |  |  |  |
| Max. volt demand L1/L12 (5) | 3700h | 8 | R | 0.1V/1V | 0 to Vmax |
| Max. volt demand L2/L23 (5) | 3701h | 8 | R | 0.1V/1V | 0 to Vmax |
| Max. volt demand L3/L31 (5) | 3702h | 8 | R | 0.1V/1V | 0 to Vmax |
| Max. ampere demand L1 | 3703h | 8 | R | 0.01A | 0 to Imax |
| Max. ampere demand L2 | 3704h | 8 | R | 0.01A | 0 to Imax |
| Max. ampere demand L3 | 3705h | 8 | R | 0.01A | 0 to Imax |
| Reserved | 3706h | 8 | R |  |  |
| Reserved | 3707h | 8 | R |  | 0 |
| Reserved | 3708h | 8 | R |  | 0 |
| Max. sliding window kW demand | 3709h | 8 | R | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Reserved | 370Ah | 8 | R |  |  |
| Max. sliding window kVA demand | 370Bh | 8 | R | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| L1/ L12 voltage harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6400h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6401h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H40 angle | 6427h | 4 | R | 0.1 degree | -1800 to 1800 |
| L2/ L23 voltage harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6500h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6501h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H40 angle | 6527h | 4 | R | 0.1 degree | -1800 to 1800 |
| L3 voltage harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6600h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6601h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H40 angle | 6627h | 4 | R | 0.1 degree | -1800 to 1800 |
| L1 current harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6800h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6801h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H 40 angle | . 6 ¢ |  |  |  |  |
| Harmonic H40 angle | 6827h | 4 | R | 0.1 degree | -1800 to 1800 |
| L2 current harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6900h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6901h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H40 angle | 6927h | 4 | R | 0.1 degree | -1800 to 1800 |
| L3 current harmonic angles |  |  |  |  |  |
| Harmonic H01 angle | 6a00h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H02 angle | 6a01h | 4 | R | 0.1 degree | -1800 to 1800 |
| Harmonic H40 angle | 6a27h | 4 | R | 0.1 degree | -1800 to 1800 |

(1) For parameter limits, see Note (1) to Table 4-1
(2) When using direct wiring (PT Ratio $=1$ ), voltages are transmitted in 0.1 V units, currents in 0.01 A units, and powers in $0.001 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units. For wiring via PTs (PT Ratio > 1), voltages are transmitted in 1 V units, currents in 0.01 A units, and powers in $1 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units.
(3) New absolute min/max value (lag or lead)
(4) The actual frequency range is $45.00-65.00 \mathrm{~Hz}$
(5) When the 4LN3 or 3LN3 wiring mode is selected, the voltages will be line-to-neutral; for any other wiring mode, they will be line-to-line voltages.
(M) These parameters are logged to the Min/Max log

### 5.3 Basic Setup Registers

Table 5-8 Basic Setup Registers

| Parameter | Data index | Length | Direction | Range |
| :---: | :---: | :---: | :---: | :---: |
| Wiring mode (1) | 8600h | 4 | R/W | $\begin{aligned} & 0=3 O P 2,1=4 \mathrm{LN} 3, \\ & 2=3 \mathrm{DIR2}, 3=4 \mathrm{LL} 3, \\ & 4=30 \mathrm{P} 3,5=3 \mathrm{LN} 3, \\ & 6=3 \mathrm{LL} 3 \end{aligned}$ |
| PT ratio | 8601h | 4 | R/W | 10 to $65000 \times 0.1$ |
| CT primary current | 8602h | 4 | R/W | 1 to 6500 A |
| Power demand period | 8603h | 4 | R/W | $\begin{aligned} & 1,2,5,10,15,20,30,60 \mathrm{~min} \\ & 255=\text { external } \\ & \text { synchronization (2) } \end{aligned}$ |
| Volt/ampere demand period | 8604h | 4 | R/W | 1 to 1800 sec |
| Averaging buffer size | 8605h | 4 | R/W | 8, 16, 32 |
| Reset enable/disable | 8606h | 4 | R/W | 0 = disable, 1 = enable |
| Reserved | 8607h | 4 | R | Read as 65535 |
| The number of demand periods | 8608h | 4 | R/W | 1 to 15 |
| Reserved | 8609h | 4 | R | Read as 65535 |
| Reserved | 860Ah | 4 | R | Read as 65535 |
| Nominal frequency | 860Bh | 4 | R/W | 50, 60 Hz |
| Maximum demand load current | 860Ch | 4 | R/W | 0 to 6500 A ( $0=$ CT primary current) |

(1) For the wiring mode options, see Note to Table 4-4
(2) Synchronization of power demand interval can be made through a digital input or via communications using the Synchronize power demand interval command (see Table 5-23)

### 5.4 User Selectable Options Setup

Table 5-9 User Selectable Options Registers

| Parameter | Data index | Length | Direction | Range |
| :---: | :---: | :---: | :---: | :---: |
| Power calculation mode | 8700h | 4 | R/W | 0 = using reactive power <br> $1=$ using non-active power |
| Energy roll value (1) | 8701h | 4 | R/W | $\begin{aligned} & 0=1 \times 10^{4} \\ & 1=1 \times 10^{5} \\ & 2=1 \times 10^{6} \\ & 3=1 \times 10^{7} \\ & 4=1 \times 10^{8} \end{aligned}$ |
| Phase energy calculation mode | 8702h | 4 | R/W | $0=$ disable, 1 = enable |

(1) For short energy readings (see Table 4-1), the maximum roll value will be $1 \times 10^{8}$ for positive readings and $1 \times 10^{7}$ for negative readings.

### 5.5 Communications Setup

Table 5-10 Communications Setup Registers

| Parameter | Data index | Length | Direction | Range |
| :---: | :---: | :---: | :---: | :---: |
| Reserved | 8500h | 4 | R | Read as 65535 |
| Reserved | 8501h | 4 | R | Read as 65535 |
| Address | 8502h | 4 | R/W | 0 to 99 |
| Baud rate | 8503h | 4 | R/W | $0=110 \mathrm{bps}$ |
|  |  |  |  | $1=300 \mathrm{bps}$ |
|  |  |  |  | $2=600 \mathrm{bps}$ |
|  |  |  |  | $3=1200 \mathrm{bps}$ |
|  |  |  |  | $4=2400 \mathrm{bps}$ |
|  |  |  |  | $5=4800 \mathrm{bps}$ |
|  |  |  |  | $6=9600 \mathrm{bps}$ |
|  |  |  |  | $7=19200 \mathrm{bps}$ |
| Data format | 8504h | 4 | R/W | $0=7$ bits/even parity |
|  |  |  |  | $1=8 \mathrm{bits} / \mathrm{no} \mathrm{parity}$ |
|  |  |  |  | $2=8$ bits/even parity |
| Reserved | 8505h- | 4 | R | Read as 65535 |
|  | 8507h |  |  |  |
| ASCII compatibility mode | 8508h | 4 | R/W | $0=$ disabled, $1=$ enabled (see Note (2) to Table 4-1) |

When changing the instrument address, baud rate or data format, the new communications parameters will take effect 100 ms after the instrument responds to the master's request.

### 5.6 Alarm/Event Setpoints

Table 5-11 Setpoint Setup Locations

| Setpoint number | Setup indexes (hex) |
| :--- | :--- |
| Setpoint \#1 | $8200 \mathrm{~h}-8205 \mathrm{~h}$ |
| Setpoint \#2 | $8206 \mathrm{~h}-820 \mathrm{Bh}$ |
| Setpoint \#3 | $820 \mathrm{Ch}-8211 \mathrm{~h}$ |
| Setpoint \#4 | $8212 \mathrm{~h}-8217 \mathrm{~h}$ |
| Setpoint \#5 | $8218 \mathrm{~h}-821 \mathrm{Dh}$ |
| Setpoint \#6 | $821 \mathrm{Eh}-8223 \mathrm{~h}$ |
| Setpoint \#7 | $8224 \mathrm{~h}-8229 \mathrm{~h}$ |
| Setpoint \#8 | $822 \mathrm{Ah}-822 \mathrm{Fh}$ |
| Setpoint \#9 | $8230 \mathrm{~h}-8235 \mathrm{~h}$ |
| Setpoint \#10 | 8236h-820Bh |
| Setpoint \#11 | 823Ch-8241h |
| Setpoint \#12 | 8242h-8247h |
| Setpoint \#13 | 8248h-824Dh |
| Setpoint \#14 | 824Eh-8253h |
| Setpoint \#15 | 8254h-8259h |
| Setpoint \#16 | 825Ah-825Fh |

Table 5-12 Setpoint Setup Registers

| Parameter | Offset | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| Trigger ID | +0 | 4 | R/W | See Table 5-13 |
| Action | +1 | 4 | R/W | See Table 5-14 |
| Operate delay | +2 | 4 | R/W | $0-9999(\times 0.1 \mathrm{sec})$ |
| Release delay | +3 | 4 | R/W | $0-9999(\times 0.1 \mathrm{sec})$ |
| Operate limit | +4 | 8 | R/W | See Table 5-13 |
| Release limit | +5 | 8 | R/W | see Table 5-13 |

1. The setpoint is disabled when its trigger parameter is set to NONE. To disable the setpoint, write zero into this register.
2. When writing the setpoint registers (except in the event when the setpoint is to be disabled), it is recommended to write all the setpoint registers using a single request, or to disable the setpoint before writing into separate registers. Each written value is checked for compatibility with the other setpoint parameters; if the new value does not conform to these, the request will be rejected.
3. Operate and release limits for the trigger parameters and their ranges are indicated in Table 5-13. Limits indicated as N/A are read as zeros. When writing, they can be omitted or should be written as zeros.
4. When a setpoint action is directed to a relay allocated to output energy pulses, an attempt to re-allocate it for a setpoint will result in a negative response.

Table 5-13 Setpoint Triggers

| Trigger parameter | Trigger index (hex) | Unit (2) | Range (1) |
| :---: | :---: | :---: | :---: |
| None | 0000h |  | N/A |
| Status inputs |  |  |  |
| Status input ON | 0600h |  | N/A |
| Status input OFF | 8600h |  | N/A |
| Phase reversal |  |  |  |
| Positive phase rotation reversal (3) | 8901h |  | N/A |
| Negative phase rotation reversal (3) | 8902h |  | N/A |
| High/ low real-time values on any phase |  |  |  |
| High voltage (5) | 0E00h | 0.1V/1V | 0 to Vmax |
| Low voltage (5) | 8D00h | 0.1V/1V | 0 to Vmax |
| High current | 0E01h | 0.01A | 0 to Imax |
| Low current | 8D01h | 0.01A | 0 to Imax |
| High voltage THD | 0E07h | 0.1\% | 0 to 9999 |
| High current THD | 0E08h | 0.1\% | 0 to 9999 |
| High K-Factor | 0E09h | 0.1 | 10 to 9999 |
| High current TDD | 0E0Ah | 0.1\% | 0 to 1000 |
| High/ low real-time auxiliary values |  |  |  |
| High frequency (4) | 1002h | 0.01 Hz | 0 to 10000 |
| Low frequency (4) | 9002h | 0.01 Hz | 0 to 10000 |
| High/ low average values per phase |  |  |  |
| High current L1 | 1103h | 0.01A | 0 to Imax |
| High current L2 | 1104h | 0.01A | 0 to Imax |
| High current L3 | 1105h | 0.01A | 0 to Imax |
| Low current L1 | 9103h | 0.01A | 0 to Imax |
| Low current L2 | 9104h | 0.01A | 0 to Imax |
| Low current L3 | 9105h | 0.01A | 0 to Imax |
| High/ low average values on any phase |  |  |  |
| High voltage (5) | 1300h | 0.1V/1V | 0 to Vmax |
| Low voltage (5) | 9200h | 0.1V/1V | 0 to Vmax |
| High current | 0301h | 0.01A | 0 to Imax |
| Low current | 8201h | 0.01A | 0 to Imax |
| High/ low average total values |  |  |  |
| High total kW import | 1406h | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| High total kW export | 1407h | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| High total kvar import | 1408h | 0.001kvar/1kvar | 0 to Pmax |
| High total kvar export | 1409h | 0.001kvar/1kvar | 0 to Pmax |
| High total kVA | 1402h | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Low total PF lag | 9404h | 0.001 | 0 to 1000 |
| Low total PF lead | 9405h | 0.001 | 0 to 1000 |
| High/ low average auxiliary values |  |  |  |
| High neutral current | 1501h | 0.01A | 0 to Imax |
| High frequency (4) | 1502h | 0.01 Hz | 0 to 10000 |
| Low frequency (4) | 9502h | 0.01 Hz | 0 to 10000 |
| High present demands |  |  |  |
| High volt demand L1/L12 (5) | 1600h | 0.1V/1V | 0 to Vmax |
| High volt demand L2/L23 (5) | 1601h | 0.1V/1V | 0 to Vmax |


| Trigger parameter | Trigger index (hex) | Unit (2) | Range (1) |
| :---: | :---: | :---: | :---: |
| High volt demand L3/L31 (5) | 1602h | 0.1V/1V | 0 to Vmax |
| High ampere demand L1 | 1603h | 0.01A | 0 to Imax |
| High ampere demand L2 | 1604h | 0.01A | 0 to Imax |
| High ampere demand L3 | 1605h | 0.01A | 0 to Imax |
| High block kW demand | 1606h | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| High block kVA demand | 1608h | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| High sliding window kW demand | 1609h | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| High sliding window kVA demand | 160Bh | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| High accumulated kW demand | 160Fh | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| High accumulated kVA demand | 1611h | $0.001 \mathrm{kVA} / 1 \mathrm{kVA}$ | 0 to Pmax |
| Predicted kW demand (import) | 1612h | $0.001 \mathrm{~kW} / 1 \mathrm{~kW}$ | 0 to Pmax |
| Predicted kVA demand | 1614h | 0.001kVA/1kVA | 0 to Pmax |
| High voltage harmonics on any phase |  |  |  |
| High voltage harmonic H03 | 7201h | 0.01\% | 0 to 10000 |
| High voltage harmonic H05 | 7202h | 0.01\% | 0 to 10000 |
| High voltage harmonic H07 | 7203h | 0.01\% | 0 to 10000 |
| High voltage harmonic H09 | 7204h | 0.01\% | 0 to 10000 |
| High voltage harmonic H11 | 7205h | 0.01\% | 0 to 10000 |
| High voltage harmonic H13 | 7206h | 0.01\% | 0 to 10000 |
| High voltage harmonic H15 | 7207h | 0.01\% | 0 to 10000 |
| High voltage harmonic H17 | 7208h | 0.01\% | 0 to 10000 |
| High voltage harmonic H19 | 7209h | 0.01\% | 0 to 10000 |
| High voltage harmonic H21 | 720Ah | 0.01\% | 0 to 10000 |
| High voltage harmonic H23 | 720Bh | 0.01\% | 0 to 10000 |
| High voltage harmonic H25 | 720Ch | 0.01\% | 0 to 10000 |
| High voltage harmonic H27 | 720Dh | 0.01\% | 0 to 10000 |
| High voltage harmonic H29 | 720Eh | 0.01\% | 0 to 10000 |
| High voltage harmonic H31 | 720Fh | 0.01\% | 0 to 10000 |
| High voltage harmonic H33 | 7210h | 0.01\% | 0 to 10000 |
| High voltage harmonic H35 | 7211h | 0.01\% | 0 to 10000 |
| High voltage harmonic H37 | 7212h | 0.01\% | 0 to 10000 |
| High voltage harmonic H39 | 7213h | 0.01\% | 0 to 10000 |
| High current harmonics on any phase |  |  |  |
| High current harmonic H03 | 7301h | 0.01\% | 0 to 10000 |
| High current harmonic H05 | 7302h | 0.01\% | 0 to 10000 |
| High current harmonic H07 | 7303h | 0.01\% | 0 to 10000 |
| High current harmonic H09 | 7304h | 0.01\% | 0 to 10000 |
| High current harmonic H11 | 7305h | 0.01\% | 0 to 10000 |
| High current harmonic H13 | 7306h | 0.01\% | 0 to 10000 |
| High current harmonic H15 | 7307h | 0.01\% | 0 to 10000 |
| High current harmonic H17 | 7308h | 0.01\% | 0 to 10000 |
| High current harmonic H19 | 7309h | 0.01\% | 0 to 10000 |
| High current harmonic H21 | 730Ah | 0.01\% | 0 to 10000 |
| High current harmonic H23 | 730Bh | 0.01\% | 0 to 10000 |
| High current harmonic H25 | 730Ch | 0.01\% | 0 to 10000 |
| High current harmonic H27 | 730Dh | 0.01\% | 0 to 10000 |
| High current harmonic H29 | 730Eh | 0.01\% | 0 to 10000 |
| High current harmonic H31 | 730Fh | 0.01\% | 0 to 10000 |
| High current harmonic H33 | 7310h | 0.01\% | 0 to 10000 |
| High current harmonic H35 | 7311h | 0.01\% | 0 to 10000 |
| High current harmonic H37 | 7312h | 0.01\% | 0 to 10000 |
| High current harmonic H39 | 7313h | 0.01\% | 0 to 10000 |

(1) For parameter limits, see Note (1) to Table 4-1
(2) When using direct wiring (PT Ratio $=1$ ), voltages are transmitted in 0.1 V units, currents in 0.01 A units, and powers in $0.001 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units. For wiring via PTs (PT Ratio > 1), voltages are transmitted in 1 V units, currents in 0.01 A units, and powers in $1 \mathrm{~kW} / \mathrm{kvar} / \mathrm{kVA}$ units.
(3) The setpoint is operated when the actual phase sequence does not match the indicated phase rotation
(4) The actual frequency range is $45.00-65.00 \mathrm{~Hz}$
(5) When the 4LN3 or 3LN3 wiring mode is selected, the voltages will be line-to-neutral; for any other wiring mode, they will be line-to-line voltages.

## Table 5-14 Setpoint Actions

| Action | ID (hex) |
| :--- | :--- |
| No action | 0000 h |
| Operate relay \#1 | 3000 h |
| Operate relay \#2 | 3001 h |
| Operate relay \#3 | 3002 h |
| Operate relay \#4 | 3003 h |
| Operate relay \#5 | 3004 h |
| Operate relay \#6 | 3005 h |
| Operate relay \#7 | 3006 h |
| Operate relay \#8 | 3007 h |
| Assert local alarm | 3200 h |
| Increment counter \#1 | 4000 h |
| Increment counter \#2 | 4001 h |
| Increment counter \#3 | 4002 h |
| Increment counter \#4 | 4003 h |
| Count operating time using counter \#1 © | 4400 h |
| Count operating time using counter \#2 © | 4401 h |
| Count operating time using counter \#3 © | 4402 h |
| Count operating time using counter \#4 © | 4403 h |

(1) This action converts a common event counter to the time counter which measures time at 0.1 hour resolution while the setpoint is in the operated state. Each time counter has a non-volatile shadow counter that counts time at 1 -second resolution before the corresponding time counter is incremented.

### 5.7 Relay Operation Control Registers

These registers allow the user to manually override setpoint relay operations. Either relay may be manually forced operated or released using commands sent via communications.

## NOTES

1. A relay allocated as a pulsing relay may not be manually operated or released. When a relay is allocated for pulsing, it automatically reverts to normal operation.
2. A relay is energized when forced operated, and is de-energized when forced released.

Table 5-15 Relay Operation Control Registers

| Parameter | Data <br> index | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| Relay \#1 control status | 8400 h | 4 | R/W | See Table 5-16 |
| Relay \#2 control status | 8401 h | 4 | R/W | See Table 5-16 |
| Relay \#3 control status | 8402 h | 4 | R/W | See Table 5-16 |
| Relay \#4 control status | 8403 h | 4 | R/W | See Table 5-16 |
| Relay \#5 control status | 8404 h | 4 | R/W | See Table 5-16 |
| Relay \#6 control status | 8405 h | 4 | R/W | See Table 5-16 |
| Relay \#7 control status | 8406 h | 4 | R/W | See Table 5-16 |
| Relay \#8 control status | 8407 h | 4 | R/W | See Table 5-16 |

Table 5-16 Relay Operation Status

| Operation status | ID |
| :--- | :--- |
| Normal operation | 0 |
| Force operate | 1 |
| Force release | 2 |

### 5.8 Instrument Options Registers

Table 5-17 Instrument Options Registers

| Parameter | Data <br> index | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| Options 1 register | 7F00h | 4 | R | See Table 5-18 |
| Options 2 register | 7F01h | 4 | R | See Table 5-18 |

Table 5-18 Instrument Options

| Options register | Bit | Description |
| :--- | :--- | :--- |
| Options1 | 0 | 120 V option |
|  | 1 | 690V option |
|  | $2-5$ | N/A |
|  | 6 | Analog output 0/4-20 mA |
|  | $7-8$ | N/A |
|  | 9 | Relays option |
|  | 10 | Digital input option |
|  | $11-12$ | N/A |
|  | 13 | ASClI compatibility mode enabled (see Table 5-10) |
| Options 2 | $14-15$ | N/A |
|  | $0-2$ | Number of relays - 1 |
|  | $3-6$ | Number of digital inputs - 1 |
|  | $7-15$ | N/A |

### 5.9 Extended Status Registers

## Table 5-19 Extended Status Registers

| Parameter | Data <br> index | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| Relay status | 7D00h | 4 | R | See Table 4-12 |
| Reserved | 7D01h | 4 | R | Read as 0000 |
| Status inputs | 7D02h | 4 | R | See Table 4-13 |
| Setpoint status | 7D03h | 4 | R | See Table 4-14 |
| Log status | 7D04h | 4 | R | See Table 4-15 |

### 5.10 Alarm Status Registers

## Table 5-20 Alarm Status Registers

| Parameter | Data <br> index | Length | Direction | Range |
| :--- | :--- | :--- | :--- | :--- |
| Setpoint alarm status <br> Self-check alarm status | 7E00h | 4 | R/W | see Table 5-21 |
|  | 7E01h | 4 | R/W | see Table 5-22 |

The setpoint alarm register stores the status of the operated setpoints by setting the appropriate bits to 1 . The alarm status bits can be reset all together by writing zero to the setpoint alarm register. It is possible to reset each alarm status bit separately by writing back the contents of the alarm register with a corresponding alarm bit set to 0 .

The self-check alarm register indicates possible problems with the instrument hardware or setup configuration. The hardware problems are indicated by the appropriate bits which are set whenever the instrument fails self-test diagnostics or in the event of loss of power. The setup configuration problems are indicated by the dedicated bit which is set when either configuration register is corrupted. In this event, the instrument will use the default configuration. The configuration corrupt bit may also be set as a result of the legal changes in the setup configuration since the instrument might implicitly change or clear other setups if they are affected by the changes made.

Hardware fault bits can be reset by writing zero to the self-check alarm register. The configuration corrupt status bit is also reset automatically when you change setup either via the front panel or through communications.

## Table 5-21 Setpoint Alarm Status

| Bit |  |
| :--- | :--- |
| 0 | Alarm \#1 |
| 1 | Alarm \#2 |
| 2 | Alarm \#3 |
| 3 | Alarm \#4 |
| 4 | Alarm \#5 |
| 5 | Alarm \#6 |
| 6 | Alarm \#7 |
| 7 | Alarm \#8 |
| 8 | Alarm \#9 |
| 9 | Alarm \#10 |
| 10 | Alarm \#11 |
| 11 | Alarm \#12 |
| 12 | Alarm \#13 |
| 13 | Alarm \#14 |
| 14 | Alarm \#15 |
| 15 | Alarm \#16 |

Bit meaning: 1 = setpoint has been operated

## Table 5-22 Self-check Alarm Status

| Bit | $\quad$ Description |
| :--- | :--- |
| 0 | Reserved |
| 1 | ROM error |
| 2 | RAM error |
| 3 | Watchdog timer reset |
| 4 | Sampling failure |
| 5 | Out of control trap |
| 6 | Reserved |
| 7 | Timing failure |
| 8 | Loss of power (power up) |
| 9 | External reset (warm restart) |
| 10 | Configuration corrupted |
| $11-15$ | Reserved |

### 5.11 Reset/Synchronization Registers

Table 5-23 Reset/Synchronization Registers

| Action | Data index | Length | Direction | Range |
| :---: | :---: | :---: | :---: | :---: |
| Clear total energy registers Clear total maximum demand registers | A000h | $\begin{aligned} & 4 \\ & 4 \end{aligned}$ | $\begin{aligned} & W \\ & W \\ & W \end{aligned}$ | $\begin{aligned} & 0 \\ & 0=\text { all maximum demands } \\ & 1=\text { power demands } \\ & 2=\text { volt/ampere demands } \end{aligned}$ |
| Reserved | $\begin{aligned} & \text { A002h - } \\ & \text { A003h } \end{aligned}$ | 4 |  |  |
| Clear event/time counters | A004h | 4 | W | $\left\lvert\, \begin{aligned} & 0=\text { all counters } \\ & 1-4=\text { counter \#1-\#4 } \end{aligned}\right.$ |
| Clear Min/Max log |  | 4 | W | 0 |
| Reserved | $\begin{aligned} & \text { A006h - } \\ & \text { A00Fh } \end{aligned}$ | 4 |  |  |
| Synchronize power demand interval (1) | A010h | 4 | W | 0 |

(1) 1) If the power demand period is set to External Synchronization (see Table 5-8), writing a zero to this location will simulate an external synchronization pulse denoting the start of the next demand interval. The synchronization requests should not follow in intervals of less than 30 seconds, or the request will be
rejected. This function is not permitted if the external synchronization is implemented by hardware, i.e., the digital input is configured as an external synchronization pulse input.
2) If the power demand period is specified in minutes, writing a zero to this location provides synchronization of the instrument's internal timer with the time of reception of the master's request. If the time expired from the beginning of the current demand interval is more than 30 seconds, the new demand interval starts immediately, otherwise synchronization is delayed until the next demand interval.

## NOTES

